

Publikationen

(2018): Genauigkeitsmessung verschiedener GNSS-Empfänger. Studie zur Nutzung von GNSS-Empfängern für autonomes Fahren. Posterpräsentation. In: 5. Tag der Forschung, Deggendorf.

(2017): Augmented Reality for Digital Geo-Based Participation to Integrate Citizens in Municipality Planning Processes. In: Bavarian Journal of Applied Sciences, vol. 3, no. 1, pp. 248-260. DOI: 10.25929/zpn3-3v70.

(2016): Mapping the Surroundings as a Requirement for Autonomous Driving. In: ACTA Polytechnica CTU Proceedings (Student Conference on Planning in Artificial Intelligence and Robotics [PAIR 2016]; Deggendorf), vol. Vol. 6.