

Publikationen

(2020): Evaluation of the impact of faulty scanning trajectories in robot-based x-ray computed tomography. In: Measurement Science and Technology, vol. 32, no. 1. DOI: 10.1088/1361-6501/abaf2a.

(2019): Investigation of positioning accuracy of industrial robots for robotic-based X-ray computed tomography. In: iCT 2019 9th Conference on Industrial Computed Tomography (iCT) [13-15 February, 2019; Padua, Italy].