

Publikationen

(2016): Test concept for a mobile robot with optimized traction. In: Proceedings of ISR 2016 (47th International Symposium on Robotics, June 21-22 2016, Munich).

(2015): Kettenantrieb für optimierte Traktion an mobilen Robotern. In: Bavarian Journal of Applied Sciences, vol. 1, no. 1, pp. 81-93. DOI: 10.25929/w2tf-ks21.